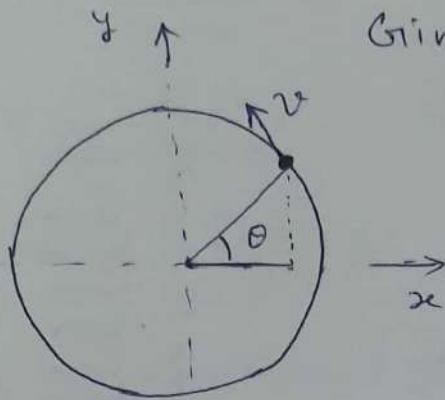


①



Given : $v = 50 \text{ cm/s}$
 $T = 6 \text{ s}$
 $\theta (t=0) = 33^\circ$
 $\omega = 60^\circ/\text{s}$

(a) x-co-ordinate follows: $x = A \cos(\omega t + \alpha)$

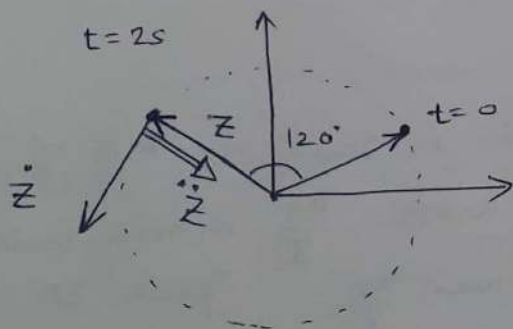
Amp. \equiv Radius of circle

$$A = \frac{v}{\omega} = \frac{v}{2\pi/T} = \frac{50}{(6.28/6)} \approx 50 \text{ cm}$$

$$\omega = 2\pi/T \quad \& \quad \alpha = 30^\circ$$

(b)
$$\left. \begin{aligned} x &= A \cos(\omega t + \alpha) \\ \dot{x} &= -A\omega [\sin(\omega t + \alpha)] \\ \ddot{x} &= -A\omega^2 \cos(\omega t + \alpha) \end{aligned} \right\} \text{ case } t = 2 \text{ s}$$

(c) $\theta (t=0) = 30^\circ$
 $\theta (t=2\text{s}) = 30 + 120$
 $\quad \quad \quad = 150^\circ$



z - position
 \dot{z} = velocity
 \ddot{z} = Acceleration

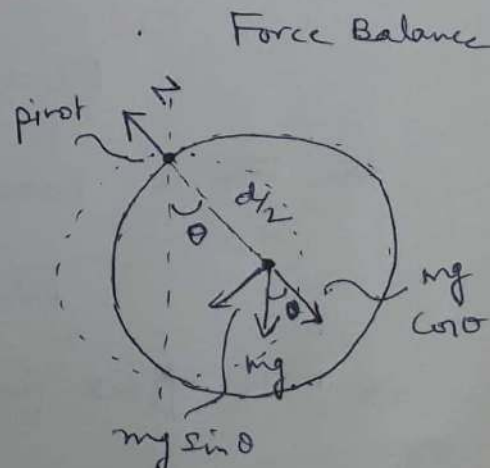
Q-2

Eqⁿ of motion

Torque $I \ddot{\theta} = -mg \sin \theta \cdot \frac{d}{2}$

$$\Rightarrow \omega = \sqrt{\frac{mgd}{2I}}$$

Moment of inertia $I = I_{cm} + M \left(\frac{d}{2}\right)^2$
 $= M \left(\frac{d}{2}\right)^2 + M \left(\frac{d}{2}\right)^2$

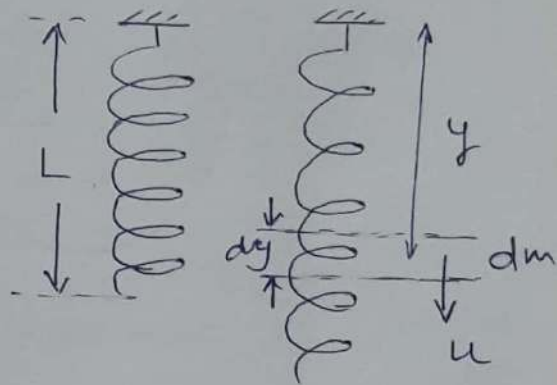


Using above:

$$\omega = \sqrt{\frac{g}{d}}$$

Q-3 Consider a real spring of uniform mass density

- Let a mass element dm at distance y from pivot moves with u



Total KE:
$$T = \int_0^L \frac{1}{2} u^2 dm$$

Uniform spring $dm = \frac{dy}{L} m$

& $u = \frac{v}{L} y$ (lower point moves faster)

$$\Rightarrow T = \int_0^L \frac{1}{2} u^2 \frac{m}{L} dy$$

$$= \frac{m}{2L} \int_0^L u^2 dy$$

$$= \frac{1}{2} \frac{m}{L} \int_0^L \frac{1}{L} y^2 v^2 dy$$

$$T = \frac{1}{2} \frac{m}{3} v^2$$

This is same as KE of a mass $\frac{m}{3}$ moving with speed v

\Rightarrow For real spring effective mass $\frac{m}{3}$

$$\omega_0 = \sqrt{\frac{k}{m/3}}$$

\Rightarrow For a loaded real spring

$$\omega_0 = \sqrt{\frac{k}{M + m/3}}$$

$$\omega_0^2 = \frac{k}{M'}$$

$$2 \frac{\Delta \omega_0}{\omega_0} = \frac{\Delta M'}{M'}$$

\Rightarrow Frq. offset for $m = M/10$

$$\Rightarrow \frac{\Delta \omega_0}{\omega_0} = \frac{1}{2} \left(\frac{0.1}{3} \right) \approx 2\%$$

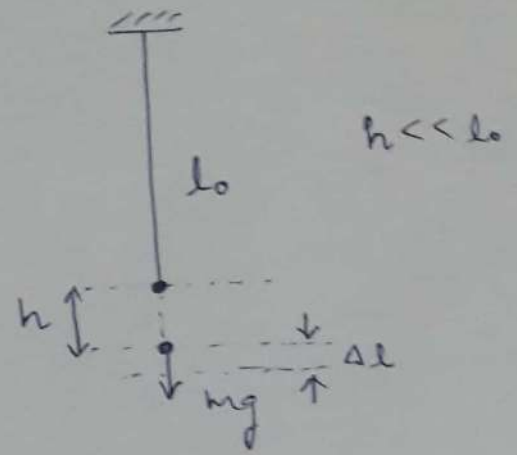
Q-5

Young's mod.

$$Y = \frac{\text{stress}}{\text{strain}} \text{ Nm}^{-2}$$

$$Y = \frac{-\Delta F/A}{\Delta l/l}$$

$$\Rightarrow dF = -\left(\frac{YA}{l}\right) \Delta l$$



if $\Delta l \rightarrow$ displacement from equil.

$$m \ddot{x} = -\left(\frac{YA}{l_0}\right) x$$

$$\Rightarrow \omega_0^2 = \frac{YA}{m l_0}$$

$$T = 2\pi \sqrt{\frac{l_0 m}{AY}}$$

At equilibrium: $mg = \frac{YA}{l_0} h$ (permanent elongation)

$$\Rightarrow \frac{mg}{AY} = \frac{h}{l_0}$$

$$T = 2\pi \sqrt{\frac{h}{g}}$$

Period same as simple pendulum of length h !
(some kind of micro-pendulum)

Example: IF $h = 10^{-3} \text{ m}$ & $l_0 = 1 \text{ m}$

$$T = 2\pi \sqrt{\frac{10^{-3}}{10}} \\ = 20\pi \text{ ms}$$